

# Optimal Stopping with Randomly Arriving Opportunities to Stop

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# Classical optimal stopping problems

- ▶ Optimally stop a reward process  $Z_t$  at some predetermined moments:
  - ▶ Bermudan, stop rewards  $Z_t$  at predetermined  $t \in \{t_1, \dots, t_k\}$ .
  - ▶ American, stop rewards  $Z_t$  at any  $t \in [0, T]$ .
- ▶ Moments may not be predetermined in practice:
  - ▶ Practical constraints: *illiquid markets, real options*.
  - ▶ Inherent randomness: *catastrophe derivatives, uncertainty of success*.
- ▶ We look at a generalization of Bermudan stopping problems:
  - ▶ (Some of) the opportunities arrive randomly
  - ▶ The terms opportunities, buyers and arrivals will be associated with each-other for the purpose of this talk.

## Leading example: valuable asset

- ▶ Suppose you have an exclusive, illiquidly traded house or piece of art.
- ▶ May be sold at the prevailing market price  $X_t$ .
- ▶ Selling requires a buyer to arrive.
- ▶ Attach a personal, non-monetary value  $C$ , e.g. derived from utility, so only sell if  $X_t > C$ .
- ▶ Reward process:  $Z_t = e^{-rt}(X_t - C)^+$ , a call-option arises naturally here.
- ▶ Total value of the house: value of optimally stopped reward process +  $C$ .

# Feedback

- ▶ Arrivals of opportunities and prices may be interrelated.
- ▶ E.g. in our example
  - ▶ If prices are high, fewer buyers may arrive.
  - ▶ When buyers arrive this may reveal new information, affecting prices.

# Literature

Special case: opportunities arrive according to a Poisson process.

- ▶ Dupuis and Wang (2002): Perpetual call option, independent arrivals
- ▶ Hobson (2021): Shape of the value function, arrival rate depends on price dynamics
- ▶ Lange et al. (2020): develop a finite difference method for independent arrivals.

Related problems:

- ▶ Matsumoto (2006): Optimal portfolio selection, independent randomly arriving adjustment dates
- ▶ Pham and Tankov (2008, 2009): Optimal investment and consumption choice

Our contribution:

- ▶ Tackle more general feedback/dependence structures

# Problem formulation

- ▶ Sequence of  $(\mathcal{F}_t)_{t \geq 0}$ -stopping times  $0 < \tau_1 < \tau_2 < \dots$ , e.g. event times of a Poisson process, where  $\tau_k \rightarrow \infty$  a.s.
- ▶ Fixed time-horizon  $T < \infty$ .
- ▶  $Z_t = f(t, X_t)$  non-negative reward process where  $X_t$  is a  $(\mathcal{F}_t)_{t \geq 0}$ -adapted Markov process.
- ▶ Problem: optimally stop  $Z_t$  at one of the stopping times  $\tau_k \leq T$  to receive  $Z_{\tau_k}$ .
- ▶ Question: what is the optimal value  $Y_0 = \sup_{\tau \in \mathcal{T}(\tau_1, \tau_2, \dots)} \mathbb{E}[Z_\tau \mathbf{1}_{\tau \leq T}]$ ?
- ▶ Question: what is the corresponding optimal stopping rule?

# Numerical approaches

- ▶ When we allow for feedback, we are typically thinking about higher-dimensional situations (in the order of dimensions 4-10).
- ▶ Some possible approaches would be:
  - ▶ Bermudan/American approximation: may be inefficient, especially when there are only few expected arrivals.
  - ▶ Equivalent problem: American optimal stopping problem with  $\tilde{Z}_t = Z_t \mathbb{1}_{\{\exists k, t=\tau_k\}}$ : this is a continuous-time optimal stopping problem with  $\text{làdlàg}$  rewards.
  - ▶ Finite-difference or finite-elements methods (such as Lange et al. (2020)): we face the curse of dimensionality, especially in the face of feedback.
- ▶ We thus need some other approach, more tailored to the problem at hand!

## Changing perspectives

- ▶ Observation: The dynamics of interest all happen at the random times.
- ▶ We can focus our attention on these random times, jumping from random time to random time.
- ▶ New process  $\{Z_{\tau_k}\}_{k \in \mathbb{N}}$  and filtration  $\{\mathcal{F}_{\tau_k}\}_{k \in \mathbb{N}}$ .
- ▶ This is now a discrete-time, infinite horizon problem!



# Equivalence

- ▶ Original problem:  $Y_0 = \sup_{T \in \mathcal{T}(\tau_1, \tau_2, \dots)} \mathbb{E}[Z_T \mathbf{1}_{T \leq T}]$ .
- ▶  $\mathcal{N}$ , the set of discrete  $\{\mathcal{F}_{\tau_k}\}_{k \in \mathbb{N}}$ -stopping times.

## Proposition (Equivalence)

$$Y_0 = \sup_{n \in \mathcal{N}} \mathbb{E}[Z_{\tau_n} \mathbf{1}_{\tau_n \leq T}].$$

# Finite-horizon approximation

- ▶ Some algorithms require a discrete-time, finite horizon problem
- ▶ We can pass to a finite horizon problem:
  - ▶ Suppose  $\mathbb{E}[\sup_i Z_{\tau_i}^2] \leq B^2 < \infty$
  - ▶ For  $K$  sufficiently large,  $Y_0^{(K)} := \sup_{\tau \in \mathcal{T}(\tau_1, \dots, \tau_K)} \mathbb{E}[Z_\tau \mathbf{1}_{\tau \leq T}]$  can then be made  $\varepsilon$ -close to  $Y_0$ .
- ▶ In fact:

## Proposition (Truncated equivalence)

$$Y_0^{(K)} = \sup_{n \in \mathcal{N}, n \leq K} \mathbb{E}[Z_{\tau_n} \mathbf{1}_{\tau_n \leq T}].$$

# Duality

## Proposition (Weak and strong duality)

Let  $\mathcal{M}_0^{\text{UI}}$  be the collection of uniformly integrable  $\{\mathcal{F}_{\tau_k}\}_{k \in \mathbb{N}}$ -martingales that start from 0. Suppose that  $\mathbb{E}[\sup_i Z_{\tau_i}^2] \leq B^2 < \infty$  and  $\sum_{j=0}^{\infty} \mathbb{P}(\tau_j \leq T)^\alpha < \infty$  for some  $0 < \alpha < 1/2$ . Then:

- i) *Weak duality:* It holds that  $Y_0 = \inf_{M \in \mathcal{M}_0^{\text{UI}}} \mathbb{E}[\sup_i (Z_{\tau_i} - M_i)]$ .
- ii) *Strong duality:* Let  $M_i^\circ := \sum_{j=1}^i Y_j - \mathbb{E}_{\mathcal{F}_{\tau_{j-1}}} [Y_j]$ ,  $i \geq 1$ ,  $M_0^\circ = 0$ . Then it holds that  $M^\circ \in \mathcal{M}_0^{\text{UI}}$  and that  $Y_0 = \sup_{i \geq 0} (Z_{\tau_i} - M_i^\circ)$  almost-surely.

- Interpretation of the new condition: the distribution of  $N_T = \sup\{j : \tau_j \leq T\}$  has tails that decay faster than  $j^{-2}$ .

# Algorithms

We can get analogues of familiar simulation-based algorithms for this random times setting:

- ▶ Primal: Longstaff and Schwartz (2001) (Least-Squares Monte-Carlo)
- ▶ Primal: Andersen (2000) (“Optimal thresholds”)
- ▶ Dual: Andersen and Broadie (2004) (requires our duality result and a primal method)

We also show that policy iteration (Kolodko and Schoenmakers, 2006), a recursive method to obtain increasingly better approximate policies:

- ▶ extends to the infinite horizon case,
- ▶ applies to the random times situation
- ▶ and has the necessary convergence properties.

## Flexibility of the framework

The above algorithms are examples; other simulation based algorithms could be used, such as:

- ▶ local regression approaches
- ▶ COS method
- ▶ etc.

Model assumptions are minimal, many familiar dynamics can be used, e.g.:

- ▶ Underlying: GBM, Ornstein-Uhlenbeck, Heston-SVJ
- ▶ Arrivals: doubly stochastic Poisson, (Markovian) Hawkes, generalized intensity
- ▶ Interaction: arrivals with threshold, state-dependent probability of success, embedded in a multivariate Hawkes process

## Example: Max-call on Poisson random times, set-up

- ▶ Benchmark in the literature: Example 1 of Andersen and Broadie (2004):
  - ▶ Payoff on two GBMs  $(\max\{X_t^1, X_t^2\} - K)^+$ ,  $K = 100$ .
  - ▶ Usually: Bermudan stopping problem, 9 equidistant stopping opportunities on  $[0, T]$  with  $T = 3$ .
- ▶ Random-times counterpart: Poisson arriving stopping opportunities with rate  $\lambda$
- ▶ Extends to feedback

## Example: square payoff on Poisson random times, methods

- ▶ Primal algorithm: Least-Squares Monte-Carlo
  - ▶ Make approximate optimal decisions through estimated continuation values
  - ▶ Estimate through backward recursion
- ▶ Dual algorithm: Andersen-Broadie dual algorithm, uses our duality result
- ▶ Let  $X_t^{(1)} = \max\{X_t^1, X_t^2\}$  and  $X_t^{(2)} = \min\{X_t^1, X_t^2\}$ .
- ▶ We then use the regression variables  $\phi_i(t)(X_t^{(m)})^j$  and  $(X_t^{(1)})^j(X_t^{(2)})^k$ , where  $i \in \{0, 1, 2, 3, 4, 5\}$ ,  $j, k \in \{0, 1, 2, 3\}$  and  $m \in \{1, 2\}$  and  $\phi_i$  is the  $i$ 'th Laguerre polynomial

## Example: Max-call on Poisson random times, results

$X_0$	$\lambda$	Primal	(s.e.)	Dual	(s.e.)
90	1	5.6876	0.0076	5.6950	0.0081
90	2	6.8617	0.0080	6.8754	0.0084
90	5	7.6772	0.0083	7.7168	0.0094
100	1	10.5710	0.0101	10.5769	0.0102
<b>100</b>	<b>2</b>	<b>12.3455</b>	<b>0.0104</b>	<b>12.3607</b>	<b>0.0108</b>
100	5	13.4558	0.0105	13.5195	0.0184
110	1	17.1219	0.0123	17.1269	0.0123
110	2	19.5328	0.0123	19.5600	0.0151
110	5	20.8970	0.0123	20.9724	0.0208

*Table 1:  $N = 2$ ,  $\mu = r = 5\%$ ,  $\delta = 10\%$ ,  $\sigma = 20\%$   $T = 3$ . Andersen and Broadie (2004) method: 200,000 paths for the regression step in LSMC, 2,000,000 paths to determine the primal price, 1,500 paths to determine the dual price, 10,000 to estimate the dual-martingale along each path. Maximum truncation error is 0.001.*

- Duality gaps typically between 0.05% and 0.5%.



# Example: Max-call on Poisson random times, relation to Andersen and Broadie (2004)

- ▶ In the random times case for  $X_0 = 100$ 
  - ▶  $\lambda = 1$  ( $\mathbb{E}[N_{\mathcal{T}}] = 3$ ): upper-estimate is 10.577
  - ▶  $\lambda = 2$  ( $\mathbb{E}[N_{\mathcal{T}}] = 6$ ): upper-estimate is 12.361
  - ▶  $\lambda = 5$  ( $\mathbb{E}[N_{\mathcal{T}}] = 15$ ): upper-estimate is 13.520
- ▶ In the deterministic case with 9 equidistant opportunities, the lower-estimate is 13.907, which is substantially larger.
- ▶ This is a consistent finding
  - ▶ Stochasticity of opportunities may have a sizeable effect on the value of the optimal stopping problem.
  - ▶ The effect may have either sign, as we show in our forthcoming updated preprint.

## Example: Max-call with feedback

- ▶ Extend the previous example with feedback from price to arrivals
- ▶ Idea: rate  $\lambda(t, X_t; \alpha)$ , where  $\alpha$  determines the degree of feedback
  - ▶  $\alpha < 0$ : negative feedback, high  $X_t$  leads to fewer arrivals
  - ▶  $\alpha > 0$ : positive feedback, high  $X_t$  leads to more arrivals
- ▶ “Fair comparison”: we want  $\mathbb{E}[\lambda(t, X_t; \alpha)] = \lambda$ , a constant.
- ▶ Use  $\lambda(t, x; \alpha) = (1 - \alpha)\lambda + 2\alpha F_{X_t}(x)\lambda$  for  $\alpha \in [-1, 1]$ ;  
 $F_{X_t}(x) = \mathbb{P}(X_t \leq x)$ .

## Example: Max-call with feedback, results

$X_0$	$\alpha$	Primal	(s.e.)	Dual	(s.e.)	$\mathbb{E}[\tau^*]$	$\mathbb{E}[\tau_{\text{triv}}]$
90	-1	0.3667	0.0014	0.3667	0.0014	2.8810	2.8699
90	-0.5	2.2571	0.0051	2.2582	0.0051	2.7919	2.6799
90	0	3.0870	0.0058	3.0917	0.0064	2.7537	2.5558
90	0.5	3.4832	0.0060	3.4857	0.0061	2.7441	2.4661
90	1	3.7199	0.0061	3.7244	0.0062	2.7400	2.4008
110	-1	5.4504	0.0054	5.4505	0.0054	1.9068	1.7512
110	-0.5	9.0379	0.0091	9.0389	0.0091	1.9476	1.5867
110	0	10.6375	0.0098	10.6420	0.0099	1.9879	1.4841
110	0.5	11.4425	0.0101	11.4479	0.0101	2.0201	1.4163
110	1	11.8970	0.0101	11.9028	0.0102	2.0205	1.3687

Table 2:  $N = 1$ ,  $\mu = r = 5\%$ ,  $\delta = 10\%$ ,  $\sigma = 20\%$   $T = 3$ .

- ▶ Prices increase with  $\alpha$  (here).
- ▶ Effect on  $\mathbb{E}[\tau^*]$  indeterminate.

## Conclusions and future research

- ▶ The situation studied extends the case with Bermudan opportunities.
- ▶ Allows for general feedback structures, no strong structural conditions: has potential for many financial/economic questions.
- ▶ Numerical methods work and show a sizeable effect of stochastic opportunities.
- ▶ Preprint: <https://arxiv.org/abs/2311.11098>.
- ▶ Currently: studying the effect of stochastic structure on optimal stopping decisions (next iteration of preprint):
  - ▶ Effect of stochastic arrivals vs deterministic arrivals.
  - ▶ Effect of clustered arrivals.
  - ▶ Effect of feedback in either direction between arrivals and the reward process.

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