



# Optimal business model adaptation plan for a company under an energy transition scenario

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April 4<sup>th</sup> 2024

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## Context

- Climate change:
  - Caused by human activities: [Stern and Kaufmann, 2014];
  - Requires cutting carbon emissions to Net Zero as soon as possible: the Energy Transition.
- Transition Risk:
  - "The financial risks which could result from the process of adjustment towards a lower-carbon economy" (see [Carney, 2015]);
  - Long-term risk: The tragedy of horizons.
  - Need to assess this risk in a forward-looking manner: Climate Stress-Tests
     [Bank of England, 2019, Autorité de Contrôle Prudentiel et de Résolution, 2020].
- Climate Stress-Tests modelling challenges:
  - 1 Finer granularity to bypass the lack of historical data,
  - 2 Longer time horizon,
  - 3 Dynamicity of the bank's positions and balance sheet.
- Here we focus on transition risk and corporate credit risk stress testing.

# **Our Contribution**

#### Question

How to model a company's business model adaptation to the energy transition in a given transition scenario for credit risk climate stress tests?

- Many individual pathways that lead to the same aggregated results.
- Micro-Macro Simulation: The company's characteristics determine how much adaptation is needed.
- Existing approaches:
  - Deterministic: econometric regressions on historical data
    [Alogoskoufis et al., 2021, Emambakhsh et al., 2023]), same slope or target as scenario
    [Barclays PLC, 2021];
  - Rely mainly on carbon price increases and omit costs.
- We need a stochastic approach that captures all different transmission channels of transition risk (policy, technology, sentiment see [Basel Committee on Banking Supervision, 2021]).

We propose an approach by stochastic control optimization.

# The model

# The Business model indicator

# Assumptions

- $\blacksquare$   $(\Omega, \mathcal{F}, \mathbb{P})$
- Management period : [0, T] where T is the end of the scenario.
- *N* fixed decision dates i = 0 : N 1 with constant time step  $\delta$ .
- Let  $\Delta \varepsilon_i^I$  and  $\Delta \varepsilon^S$  be the bounded time-increments of random iid processes such that  $corr(\Delta \varepsilon_i^I, \Delta \varepsilon_i^S) < 0$  for any i = 0: N with canonical filtration  $\mathcal{F}$ .
- Business model indicator / State variable:  $(X_i)_{i=0:N} := (I_i, S_i)_{i=0:N}$ .
- Sales Revenues Emissions Intensity

$$X_i^{(1)} = I_i = I_{i-1}e^{-\gamma_{i-1}\delta} \times e^{\sigma_I \Delta \varepsilon_i^I - \psi_i^I(\sigma_I)}.$$
 (3.1)

- Intensity reduction rate:  $\gamma_i \in [0, \gamma_{max}] \quad \forall i = 0 : N-1$ .
- ullet  $\psi_i^I$  the log moment generating function of  $\Delta \varepsilon_i^I$ :  $e^{\psi_i^I(\sigma_I)} = \mathbb{E}\left[e^{\sigma_I \Delta \varepsilon_i^I}\right]$ .

The company's sales revenues between i-1 and i:

■ Sales Revenues

$$X_i^{(2)} = S_i = S_{i-1} \frac{\bar{S}_i}{\bar{S}_{i-1}} e^{-\kappa \left(I_{i-1} - I_{i-1}^{\text{ref}}\right)\delta} \times e^{\sigma_S \Delta \varepsilon_i^S - \psi_i^S(\sigma_S)}.$$
 (3.2)

- with  $\bar{S}$  the sales revenues of the reference market,  $I^{\rm ref}$  the market reference for the intensity and  $\kappa \geq 0$  and  $\psi_i^S$  the log moment generating function of  $\Delta \varepsilon_i^S$ .
- We take into account: Cost pass-through, Reputation (consumer sentiment) and Demand-price elasticity shocks ([Basel Committee on Banking Supervision, 2021]).

By definition of the sales emissions intensity we have:

Emissions : 
$$E_i = I_i \times S_i$$

## The costs functions

- At each date, the company will pay a carbon tax :  $cp_i \times E_i$  with  $cp_i$  the carbon price given by the scenario.
- Investment costs :  $I^{C}$ ; is a positive, increasing and convex function of the emissions reduction rate [Grubb et al., 1993, McKinsey et al., 2009].

$$I^{C}(i, S, \gamma) = S \times c \times \alpha^{i\delta} \times \frac{\left(1 - e^{-\gamma\delta}\right)^{\beta}}{\beta},$$
 (3.3)

where c>0 is the unit abatement cost of emissions in USD,  $\alpha\in[0.8,1]$  the factor of autonomous cost decrease over time, and  $\beta\geq 2$  the exponent of the emissions reduction rate  $1-e^{-\gamma\delta}$ . Indeed, the proactive emissions reduction rate is obtained as follows:

$$\Delta E_i = E_i - E_i e^{-\gamma_i \delta}$$
$$= I_i S_i (1 - e^{-\gamma_i \delta})$$

# Statement of the problem

Similarly to [Liang and Huang, 2021], we assume that the company will choose the intensity reduction strategy  $\pi = (\gamma_0, \dots, \gamma_{N-1})$  that minimizes its total discounted costs.

# Stochastic control problem

$$J^{*}(0,x) = \inf_{\pi \in \Pi} \mathbb{E} \left[ \sum_{i=0}^{N-1} \frac{\operatorname{cp}_{i} X_{i}^{(1)} X_{i}^{(2)} + I^{C}(i, X_{i}^{(2)}, \gamma_{i})}{(1+r\delta)^{i}} + \frac{C_{N}(X_{N})}{(1+r\delta)^{N}} \mid X_{0} = x \right]$$

$$= \inf_{\pi \in \Pi} \mathbb{E} \left[ \sum_{i=0}^{N-1} \frac{C_{i}(X_{i}, \gamma_{i})}{(1+r\delta)^{i}} + \frac{C_{N}(X_{N})}{(1+r\delta)^{N}} \mid X_{0} = x \right].$$
(3.4)

where  $\Pi$  is the set of admissible strategies, meaning  $\mathcal{F}$ -adapted and such that  $\gamma_i \in [0, \gamma_{max}] \quad \forall i = 0 : N - 1.$ 

# Resolution

# Theorem: Existence of an optimal control (see [Bertsekas and Shreve, 1978])

If the following assumption is satisfied:

$$\mathbb{E}\left[\max\left(0,-\mathcal{C}_{i}(X,\gamma)\right)\right]<\infty,\quad\forall i=0:N,\quad\gamma\in[0,\gamma_{max}],\tag{$F^{+}$}$$

2 and if the infimum in:

$$\inf_{\gamma \in [0,\gamma_{max}]} \{ \mathcal{C}_i(\mathsf{x},\gamma) + \frac{1}{1+r\delta} \mathbb{E}_{\gamma} \left[ J^*(i+1,X_{i+1}) \mid X_i = \mathsf{x} \right] \}, \quad i = 0: \mathsf{N}-1, \\ \mathsf{x} \in \mathbb{R}^+ \times \mathbb{R}^+,$$

is attained for all  $x \in \mathbb{R}^+ \times \mathbb{R}^+$  with  $J^*(N,x) = \mathcal{C}_N(x)$ , then an optimal nonrandomized Markov strategy  $\pi^*(x)$  exists. This strategy is given by the dynamic programming algorithm:

$$\gamma_i: x \longmapsto \arg\min_{\gamma \in [0, \gamma_{max}]} \{ \mathcal{C}_i(x, \gamma) + \frac{1}{1 + r\delta} \mathbb{E}_{\gamma} \left[ J^*(i+1, X_{i+1}) \mid X_i = x \right] \}. \tag{4.1}$$

April 4<sup>th</sup> 2024

# **Numerical Resolution by Backward Sampling**

#### Goal

Find by backward induction  $\forall i = N-1:0$ :

$$\gamma_{i}^{*}(x) = \arg\min_{\gamma \in [0, \gamma_{max}]} \{ C_{i}(x, \gamma) + \frac{1}{1 + r\delta} \mathbb{E}_{\gamma} \left[ J^{*}(i + 1, X_{i+1}) \mid X_{i} = x \right] \}.$$
 (4.2)

#### ISSUES:

- How to compute  $J^*(i,x) := \inf_{\pi_i \in \Pi_i} J_{\pi_i}(i,x)$  ?
- How to minimize  $\mathbb{E}_{\gamma}[J^*(i+1,X_{i+1}) \mid X_i = x]$  w.r.t  $\gamma$  ? (i.e. write it as an explicit function of  $\gamma$ )

# The backward sampling trick

- $X_i^{\pi_{0:i}^{(0)}}(0, X_0)$ : the value for the state variable at j starting in  $X_i^{\pi_{0:i}^{(0)}}$  at date i and computed with a reference Markovian strategy  $\pi_{i:j}^{(0)}$ .
- Let  $X_j^{\pi_{i:j}^{(0)}}(i, X_i^{\pi_{0:i}^{(0)}})$ : the value for the state variable at j starting in  $X_i^{\pi_{0:i}^{(0)}}$  at date i and computed with admissible strategy  $\pi_{i:j}$ .

Thanks to the exponential form of the state variable, we can hop between any two trajectories computed with different admissible strategies (keeping noise constant).

$$I_{j}^{\tilde{\pi}_{i:j}}(i, X_{i}^{\pi_{0:i}^{(0)}}) = I_{j}^{\pi_{i:j}^{(0)}}(i, X_{i}^{\pi_{0:i}^{(0)}}) \exp\left(-\sum_{q=i}^{j-1} (\tilde{\gamma}_{q} - \gamma_{q}^{(0)})\delta\right), \tag{4.3}$$

$$S_{j}^{\tilde{\pi}_{i:j}}(i, X_{i}^{\pi_{0:i}^{(0)}}) = S_{j}^{\pi_{i:j}^{(0)}}(i, X_{i}^{\pi_{0:i}^{(0)}}) \exp\left(-\kappa \sum_{q=i}^{j-1} \left(I_{q}^{\tilde{\pi}_{i:q}}(i, X_{i}^{\pi_{0:i}^{(0)}}) - I_{q}^{\pi_{i:q}^{(0)}}(i, X_{i}^{\pi_{0:i}^{(0)}})\right) \delta\right). \tag{4.4}$$

This allows us to compute the best trajectory starting in date i (and the corresponding reward) without resampling data.

- I Simulate M paths for  $(X_i^{\pi_{0:i}}(0, X_0^{\pi_{0:0}^{(0)}}))_{i=0:N}$  to get controlled trajectories with an arbitrarily chosen admissible deterministic strategy  $\pi_{0:N}^{(0)}$ .
- 2 For i=N-1:0:
  - 1 Set  $J^*(i+1, X_{\cdot, i+1}^{\pi_{0:i+1}^{(0)}}) =$  $\mathbb{E}\left[\sum_{\substack{j=i+1}}^{N-1} \frac{c_j\left(x_j^{\tilde{\pi}_{i+1:j}}(_{i+1}, x_{i+1}^{\pi^{(0)}}), \tilde{\gamma}_j(x_j^{\tilde{\pi}_{i+1:j}}(_{i+1}, x_{i+1}^{\pi^{(0)}}))\right)}{(1+r\delta)^{j-i-1}} + \frac{c_N\left(x_N^{\tilde{\pi}_{i+1:N}}(_{i+1}, x_{i+1}^{\pi^{(0)}})\right)}{(1+r\delta)^{N-i-1}} \mid X_{i+1}^{\pi^{(0)}}\right]\right].$
  - 2 Approximate  $J^*$  using Least Squares on L basis functions  $\phi = \{\phi_l\}_{l=1,...,L}$ .

$$\hat{J}^*(i+1, X_{i+1}) := \sum_{l=1}^{L} \hat{\alpha}_l^i \phi_l(X_{i+1}), \tag{4.5}$$

- $\textbf{3} \ \, \mathsf{Compute} \ \, \mathbb{E}_{\gamma} \left[ \hat{J^*}(i+1,X_{i+1}) \mid X_i = x \right] \approx \mathbb{E}_{\gamma} \left[ \sum_{l=1}^L \hat{\alpha}_l^i \phi_l(F(x,\gamma)) \right] \text{ as a double integral using the conditional p.d.f.}$
- of  $(\Delta \varepsilon_{i+1}^I, \Delta \varepsilon_{i+1}^S)$  w.r.t  $X_i$  and the set of simulated points  $\{X_i^{\pi_{0:i}^{(0)}}\}$ , then update the rest of the trajectory. 4 Get  $\gamma_i^*(X)$  using a minimization algorithm on the set of simulated  $X_i$  points and by regression. Then update traiectories.
- Repeat until stability of results.

Elisa NDIAYE International Conference on Computational Finance 2024

# **Application**

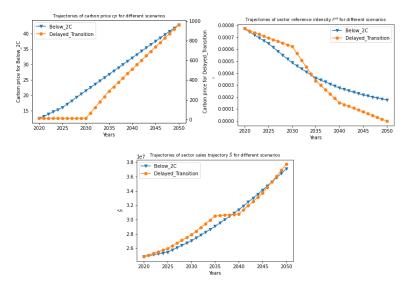


Figure: Trajectories for carbon price  $cp_i$ , reference market intensity  $I^{ref}$  and market sales  $\bar{S}$  for scenarios Below 2C and Delayed transition for D35 - Electricity Steam and Gas - France (source : NGFS)

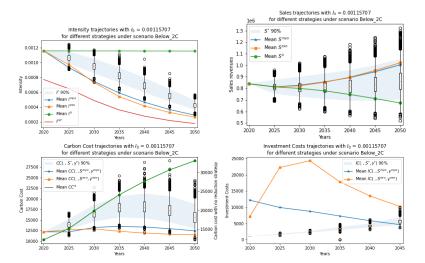


Figure: Simulated results for the **brown company** with the optimal strategy (boxplots) and benchmark strategies (myopic = stars, exogenous = squares, no strategy = dots) in scenario B2C. From top LHS to bottom RHS: Intensity, Sales Revenues, Carbon Cost and Investment Costs.

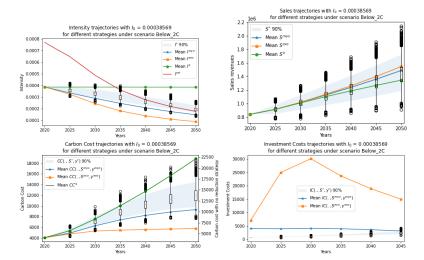


Figure: Simulated results for the **green company** with the optimal strategy (boxplots) and benchmark strategies (myopic = stars, exogenous = squares, no strategy = dots) in scenario B2C. From top LHS to bottom RHS: Intensity, Sales Revenues, Carbon Cost and Investment Costs.

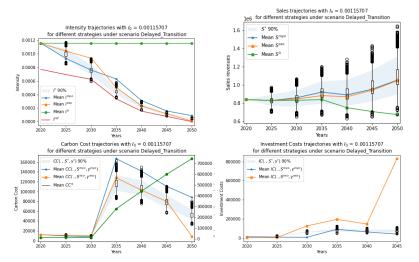


Figure: Simulated results for the **brown company** with the optimal strategy (boxplots) and benchmark strategies (myopic = stars, exogenous = squares, no strategy = dots) in scenario DT. From top LHS to bottom RHS: Intensity, Sales Revenues, Carbon Cost and Investment Costs.

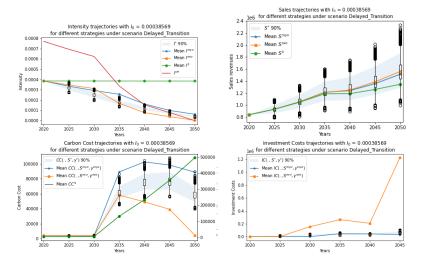


Figure: Simulated results for the **green company** with the optimal strategy (boxplots) and benchmark strategies (myopic = stars, exogenous = squares, no strategy = dots) in scenario DT. From top LHS to bottom RHS: Intensity, Sales Revenues, Carbon Cost and Investment Costs.

# **Conclusion**

- Not adapting the company's relative emissions is ill-advised for long-term credit risk assessment (carbon tax costs largely supersedes the investment economies, and loss in Sales).
- The often used exogenous strategy is overpriced for little gain in sales and carbon tax reduction.
- Myopic strategy's lack timing/anticipation can be costly, especially in disorderly transition scenarios (decreasing investment costs, carbon price shocks). (Perfect foresight assumption in stress tests)
- In general, it's best for the company to pay more tax and invest less because of the convexity of the investment costs (negligible loss in sales compared to other strategies).
- Green companies are likely to rest on their laurels and put little effort in the transition.

# Thank you for your attention

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